



西安交通大学
XI'AN JIAOTONG UNIVERSITY

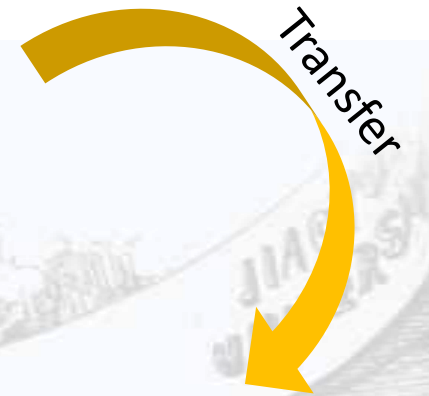
Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

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1. Unsupervised Cross-Domain Crowd Counting

➤ Goal

- Transfer **source domain** pre-trained counting model to **target domains** using **unlabeled** data.



➤ Importance

- Pre-trained model is inferior in practice due to different data distributions.
- Annotation is expensive and laborious.



1. Unsupervised Cross-Domain Crowd Counting

➤ Challenge

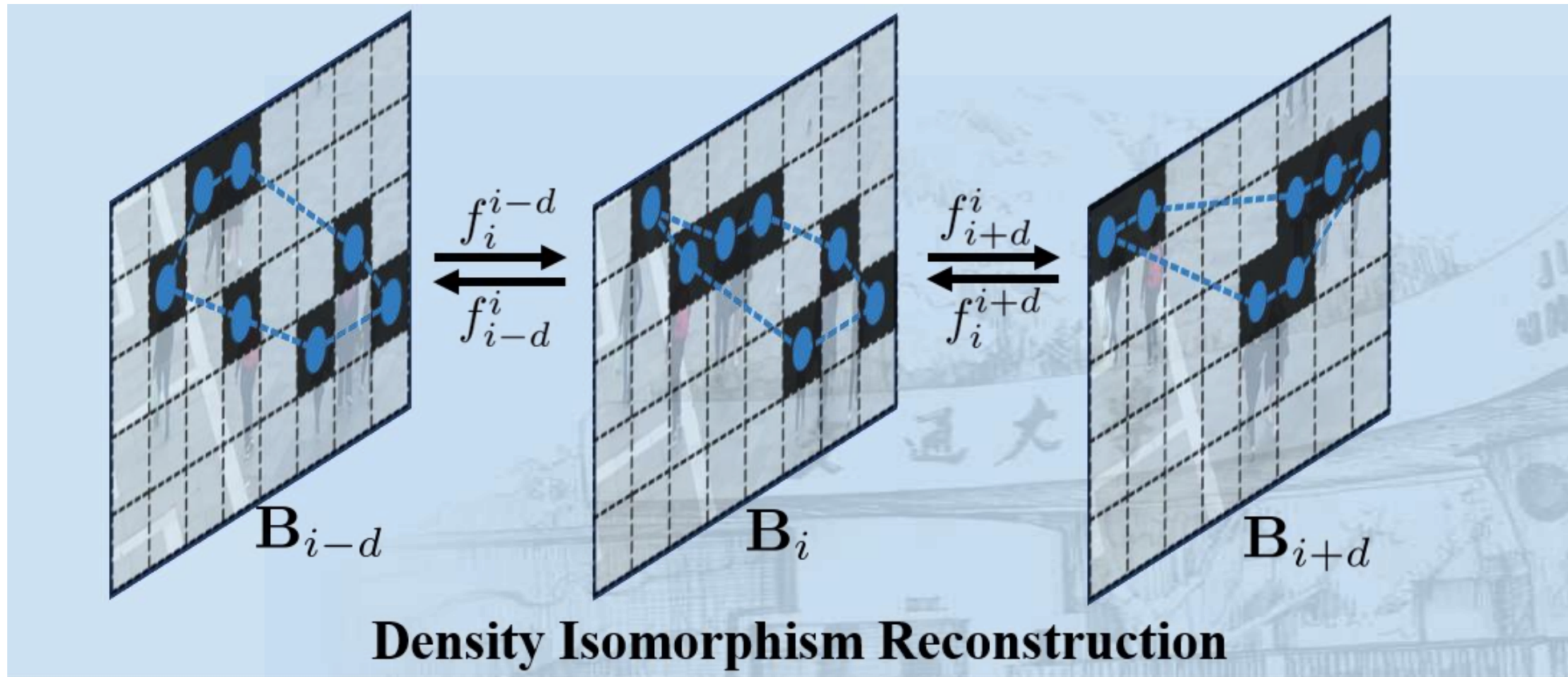
- How to **explore concealed information** in unlabeled data for knowledge transfer from source domain to unseen target domains?
- How to **measure the reliability of supervision signal**?

➤ Solutions

- Regard **density isomorphism reconstruction** as self-supervised signal.
- Model reconstruction erroneoususness using **estimation-reconstruction consistency**.

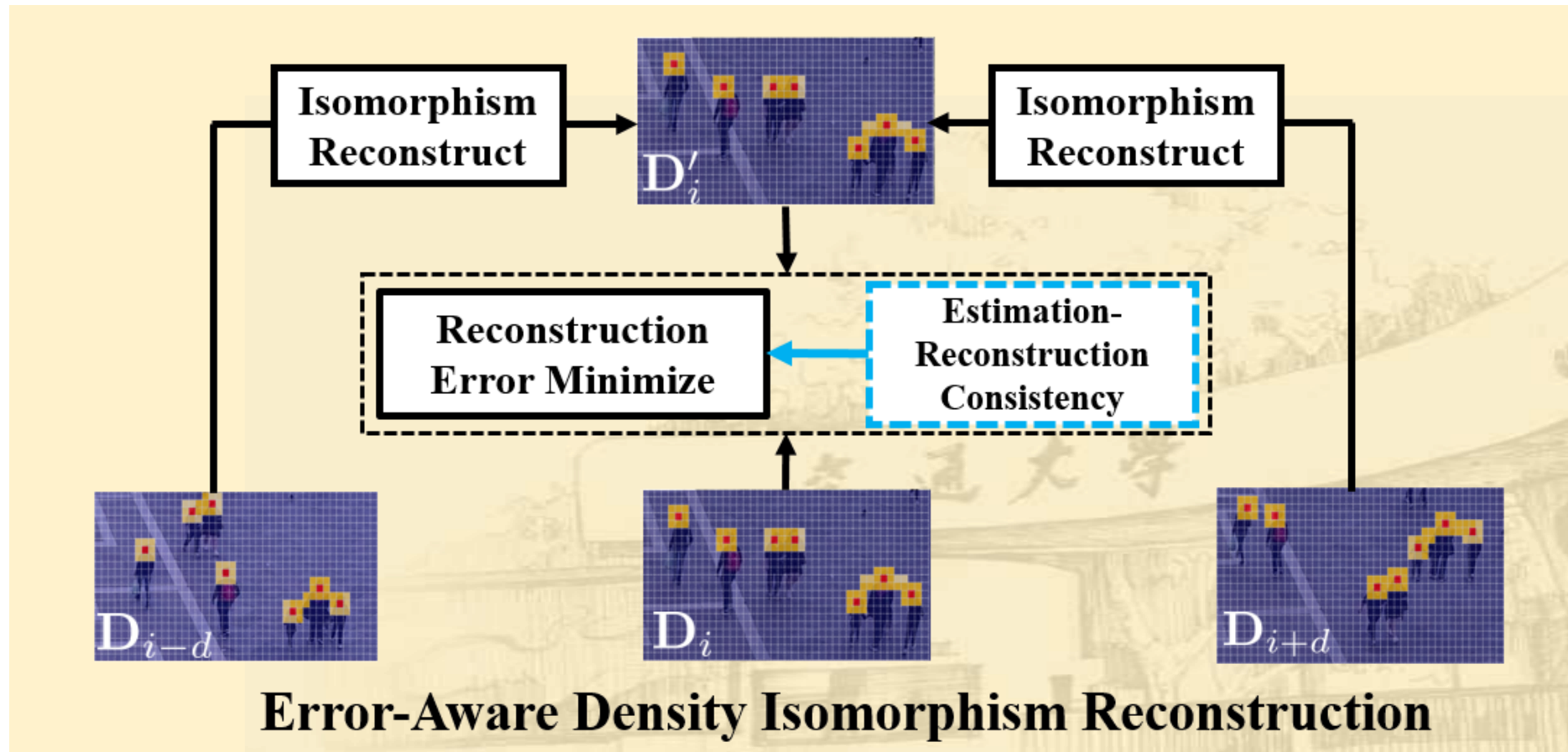
2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.1 Algorithm I: Density Isomorphism Reconstruction



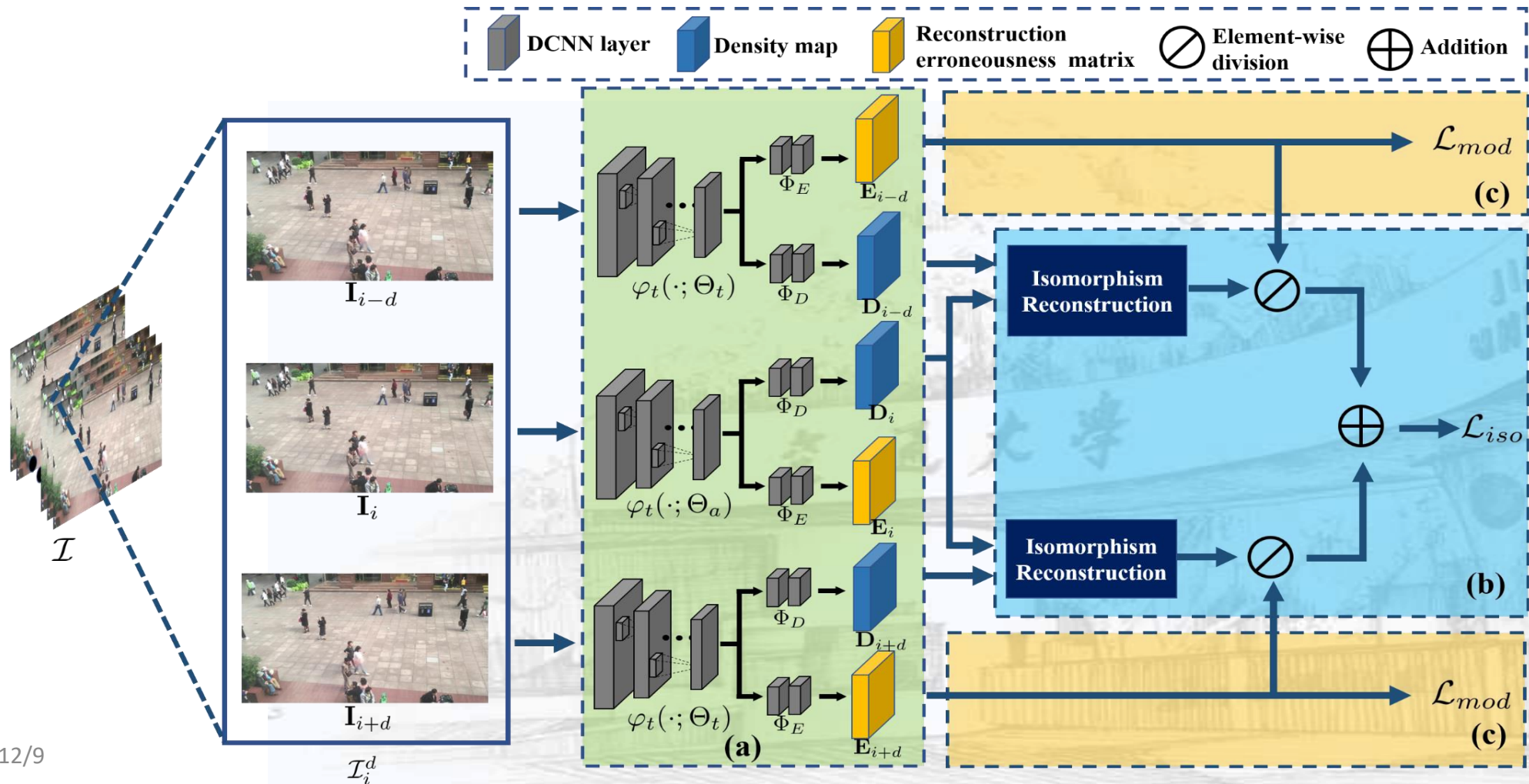
2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.1 Algorithm II: Reconstruction Erroneousness Modeling



2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.2 The Proposed Framework



2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.2 The Proposed Framework

- **Input:**

Image tuple $\mathcal{I}_i^d = \{\mathbf{I}_{i-d}, \mathbf{I}_i, \mathbf{I}_{i+d}\}$ with time interval d , where \mathbf{I}_i is the image frame at time i .

- **Density and Erroneousness Inference Module:**

Estimate a density map $\mathbf{D}_i \in \mathbb{R}_{\geq 0}^{W_D \times H_D}$ and erroneous matrix $\mathbf{E}_i \in \mathbb{R}_{\geq 0}^{W_D \times H_D}$ for each image \mathbf{I}_i .

- **Isomorphism Reconstruction Module:**

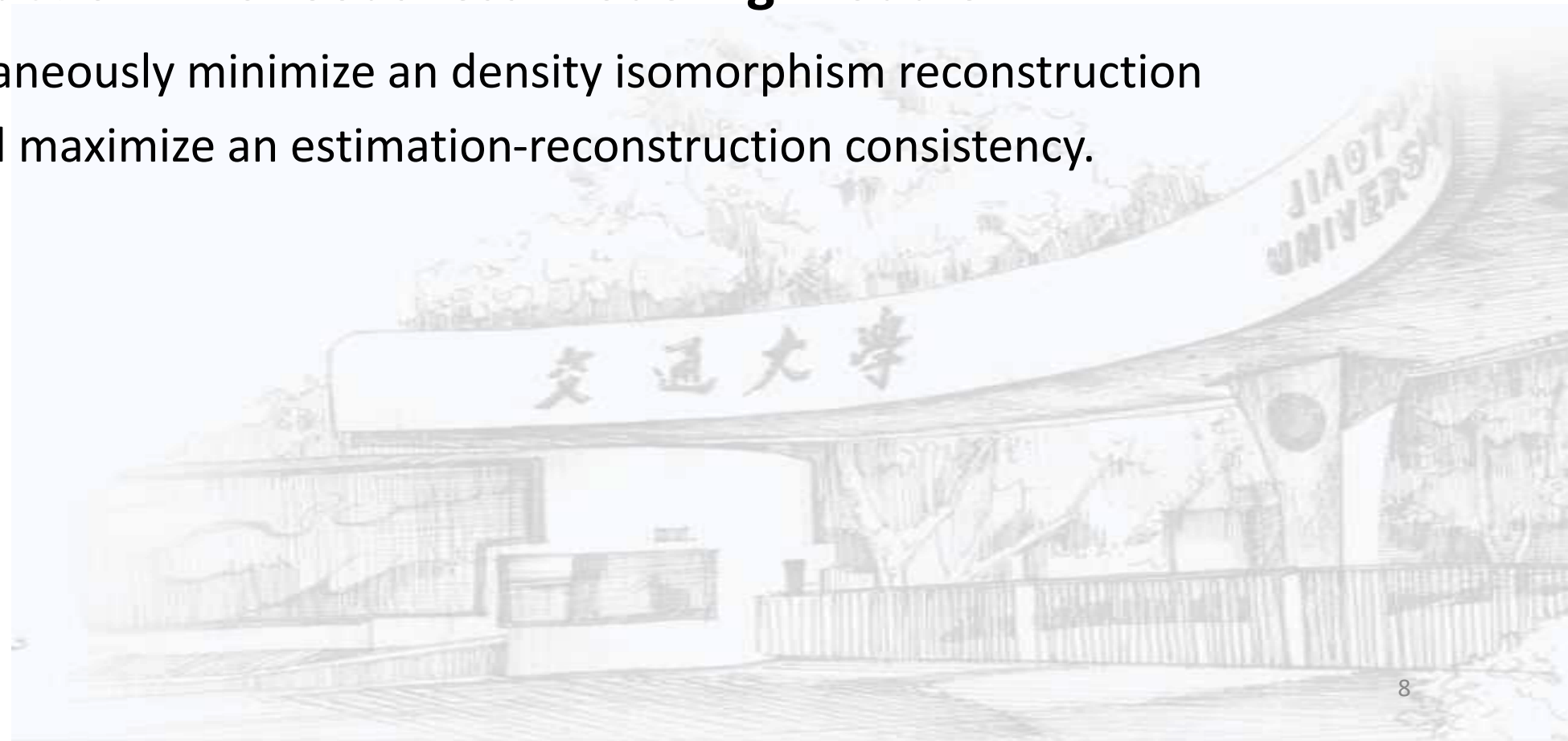
Generate a reconstructed density map $\mathbf{D}_i^{i-d'}$ (or $\mathbf{D}_i^{i+d'}$) for the i -th image using \mathbf{D}_{i-d} (or \mathbf{D}_{i+d}).

2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.2 The Proposed Framework

- **Reconstruction Erroneousness Modeling Module:**

Simultaneously minimize an density isomorphism reconstruction error and maximize an estimation-reconstruction consistency.



2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.3 Key Technique I: Density Isomorphism Reconstruction

(1). Calculate image mapping matrix

$$\mathbf{M}_i^{j*} = \operatorname{argmin}_{\mathbf{M}_i^j} \|\mathbf{I}_i - \rho(\mathbf{I}_j, \mathbf{M}_i^j)\|^2, \quad (3)$$

(2). Convert image mapping matrix to density mapping matrix

$$\mathbf{G}_i^{i-d}(u, v) = \mathbf{M}_i^{i-d} \left(\frac{W_I}{W_D} u, \frac{H_I}{H_D} v \right) \cdot \sqrt{\frac{W_D^2 + H_D^2}{W_I^2 + H_I^2}}, \quad (4)$$

$$\mathbf{G}_i^{i+d}(u, v) = \mathbf{M}_i^{i+d} \left(\frac{W_I}{W_D} u, \frac{H_I}{H_D} v \right) \cdot \sqrt{\frac{W_D^2 + H_D^2}{W_I^2 + H_I^2}}. \quad (5)$$

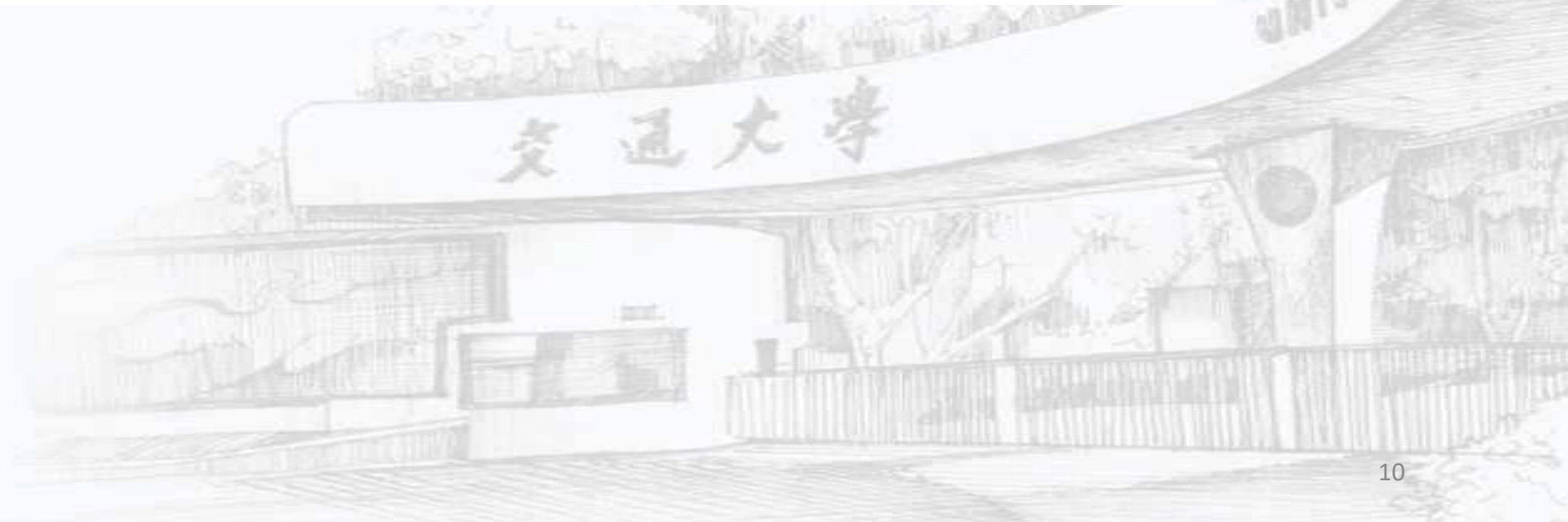
2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.3 Key Technique I: Density Isomorphism Reconstruction

(3). Reconstruct density map according to mapping matrices

$$\mathbf{D}_i^{i-d'}(x, y) = \mathbf{D}_{i-d}(u, v), \forall (x, y) = \mathbf{G}_i^{i-d}(u, v), \quad (6)$$

$$\mathbf{D}_i^{i+d'}(x, y) = \mathbf{D}_{i+d}(u, v), \forall (x, y) = \mathbf{G}_i^{i+d}(u, v), \quad (7)$$



2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.3 Key Technique II: Reconstruction Erroneousness Modeling

$$\mathcal{L}(\mathcal{I}_i^d) = \mathcal{L}_{iso}(\mathcal{I}_i^d) + \mathcal{L}_{mod}(\mathcal{I}_i^d),$$

(1) Error-aware density isomorphism reconstruction objective:

$$\mathcal{L}_{iso}(\mathcal{I}_i^d) = \left\| \left| \mathbf{D}_i - \mathbf{D}_i^{i-d'} \right|_e \oslash \mathbf{E}_{i-d} \right\|^2 + \left\| \left| \mathbf{D}_i - \mathbf{D}_i^{i+d'} \right|_e \oslash \mathbf{E}_{i+d} \right\|^2, \quad (8)$$

$$\mathbf{D}_i \in \mathbb{R}_{\geq 0}^{W_D \times H_D}$$
$$\mathbf{E}_i \in \mathbb{R}_{> 0}^{W_D \times H_D}$$

(2) Erroneousness matrix regularization term

$$\mathcal{L}_{mod}(\mathcal{I}_i^d) = \log(\mathbf{E}_{i-d}) + \log(\mathbf{E}_{i+d}),$$

2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.4 Experiment:

Table 1: Performance Evaluation on Four Benchmark Datasets.

Supervision	Method	Venice		UCSD		MALL		FDST	
		MAE↓	MSE↓	MAE↓	MSE↓	MAE↓	MSE↓	MAE↓	MSE↓
—	Baseline	33.95	39.44	7.96	8.54	4.27	5.94	4.77	8.33
Supervised	PFlow	15.00	19.60	<i>0.81</i>	<i>1.07</i>	—	—	2.84	3.57
	BL	<i>9.99</i>	<i>14.24</i>	0.84	1.08	<i>1.54</i>	<i>2.00</i>	<i>1.42</i>	<i>1.88</i>
Semi-supervised	SSR	19.84	31.13	1.68	2.07	2.69	3.38	5.41	6.13
	FSSA	<u>17.83</u>	<u>25.24</u>	<u>1.45</u>	<u>1.85</u>	<u>2.32</u>	<u>2.97</u>	<u>2.96</u>	<u>3.86</u>
Unsupervised	CSCC	18.05	22.34	8.89	9.87	4.01	4.99	5.15	7.84
	CODA	31.39	37.17	5.25	6.07	3.37	4.43	4.74	8.27
	SCP	22.79	26.52	4.55	5.71	3.03	4.04	4.28	6.74
	Ours-w/o mod	14.66	17.48	2.22	2.71	3.17	4.03	3.97	4.76
	Ours	11.23	15.16	1.79	2.47	2.36	3.12	3.25	3.94

2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

➤ 2.4 Experiment:

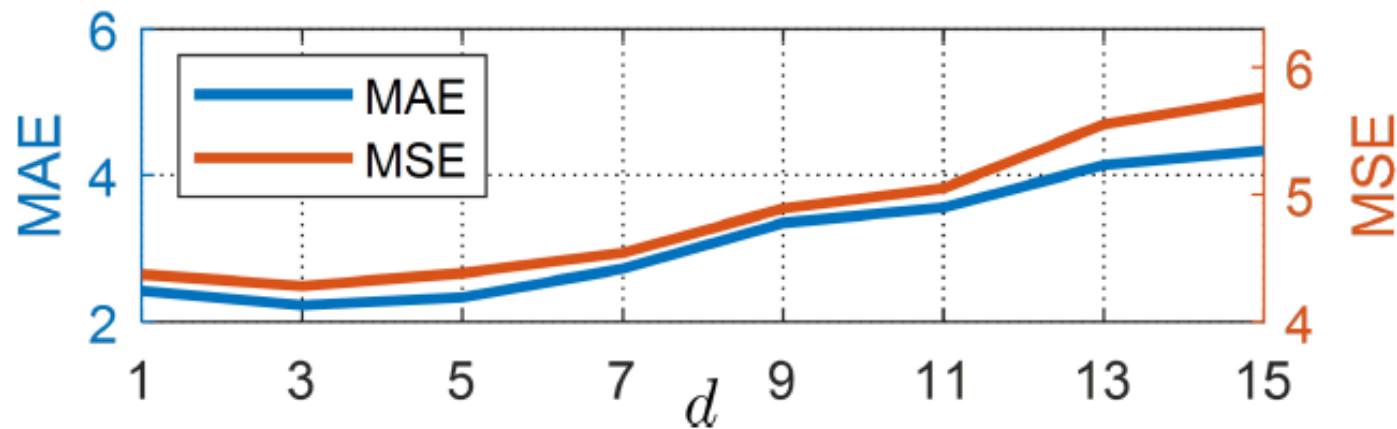


Figure 3: Influence of different d values.



2. Error-Aware Density Isomorphism Reconstruction for Unsupervised Cross-Domain Crowd Counting

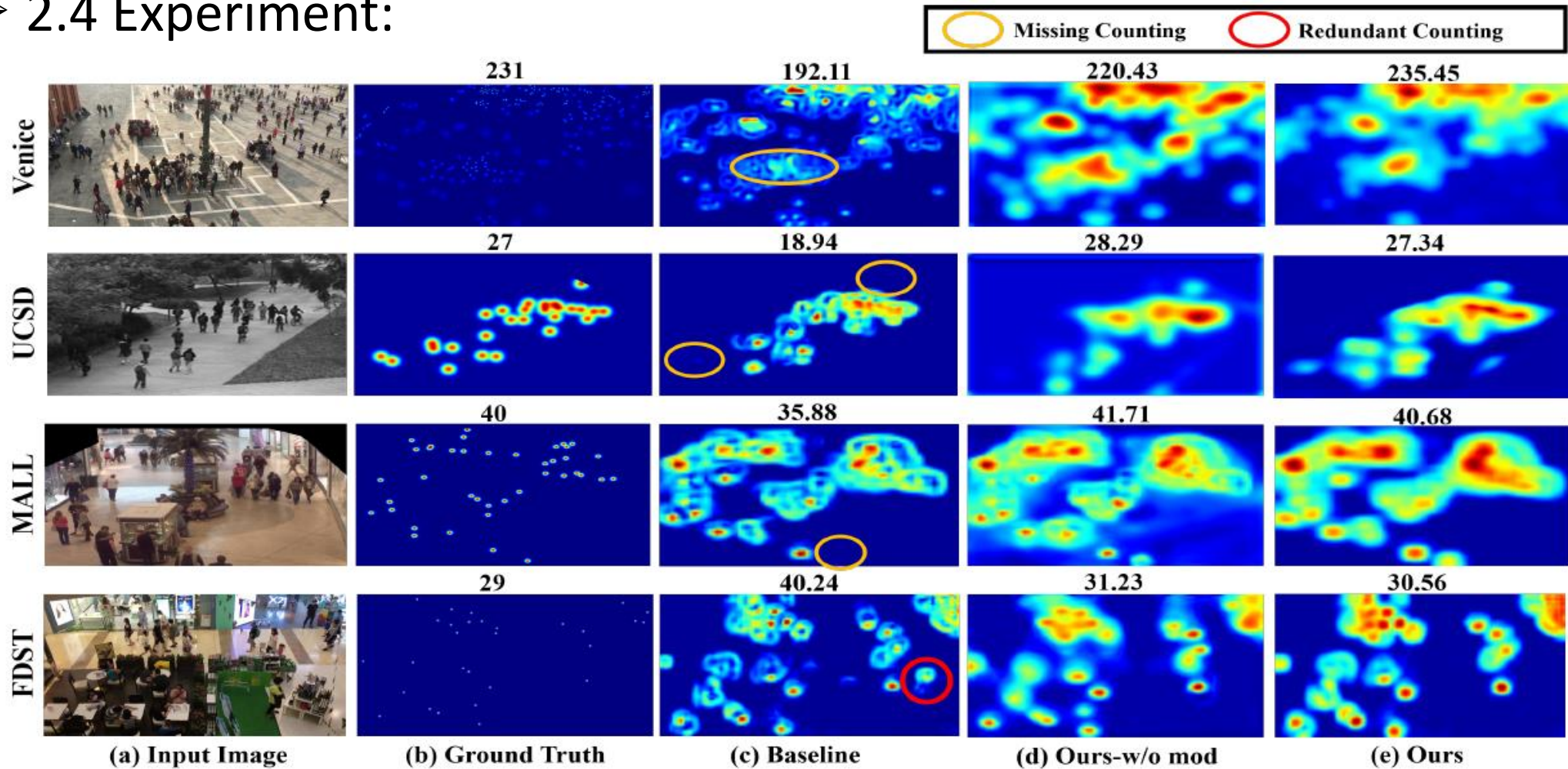
➤ 2.4 Experiment:

Table 2: Robustness to Different Pre-trained Models.

Source	Method	Venice		UCSD		MALL		FDST	
		MAE↓	MSE↓	MAE↓	MSE↓	MAE↓	MSE↓	MAE↓	MSE↓
ShanghaiTech-A	Baseline-MESA	51.57	53.68	16.80	17.81	15.67	16.75	12.80	25.59
	Ours	17.83	22.19	5.13	5.83	5.57	6.54	6.27	7.64
	Baseline-BL	40.13	51.54	15.36	16.18	12.48	12.99	5.01	8.09
	Ours	14.10	19.13	4.22	5.01	4.77	5.93	3.96	5.12
UCF-QNRF	Baseline-MESA	43.16	57.88	9.04	9.77	5.71	6.67	6.12	7.57
	Ours	13.05	15.72	2.64	3.60	4.65	6.01	4.95	6.10
	Baseline-BL	33.95	39.44	7.96	8.54	4.27	5.94	4.77	8.33
	Ours	11.23	15.16	1.79	2.47	2.36	3.12	3.25	3.94

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➤ 2.4 Experiment:



Thank you

